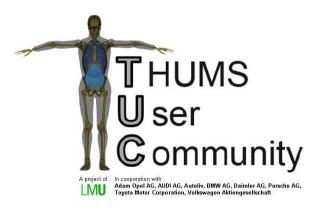
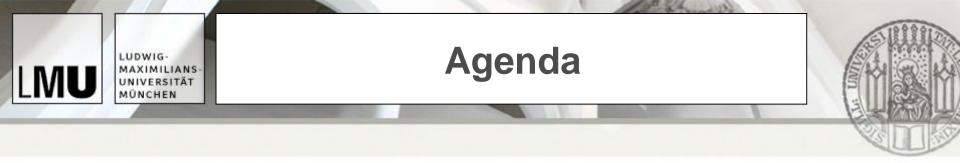


# **THUMS User Community**

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Munich, 9th of April 2014





- 1. What is THUMS User Community ?
  - a. Background
  - b. Motivation
  - c. Aims and Objectives
- 2. Process to THUMS TUC
- 3. Validation Catalogue A results



### **Project Partners**

**Core Partners** 



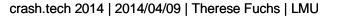
**Associated Partners** 



**VA** 

#### Subcontractor







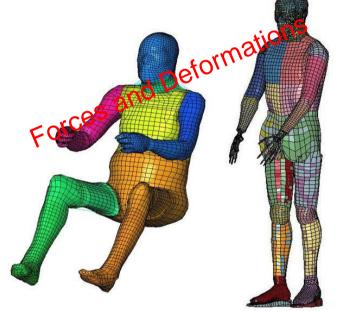
Background



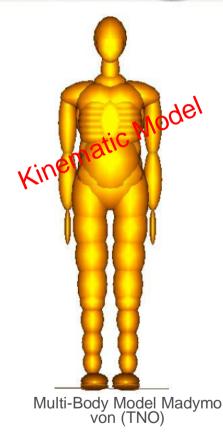
Chrashtest Dummy Family: Hybrid III



Virtual Dummy-Models



Finite-Element Human Body Models (HBM) HUMOS (EU Project) and THUMS 3 (TMC)

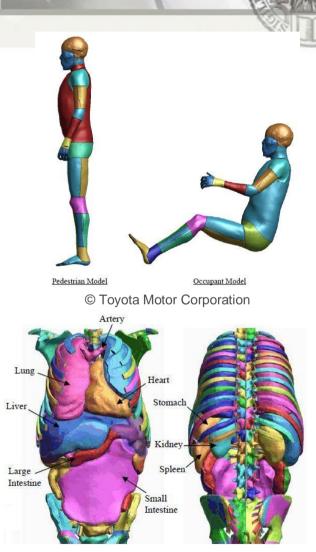


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#### **Finite-Element Human Body Models**

- Based on real geometries gathered from CT or MRI scans
- Definition of material models and parameters (e.g. Young's Modulus)
- ✓ Gain in importance in the field of passive safety
- ✓ Several advantages of HBMs towards Dummies:
  - ✓ High biofidelity
  - Simulation of stress and strain distribution within tissues
  - Estimation of injuries possible, e.g. rib fracture, injuries of internal organs
  - ✓ Influence of muscle activity



© Toyota Motor Corporation



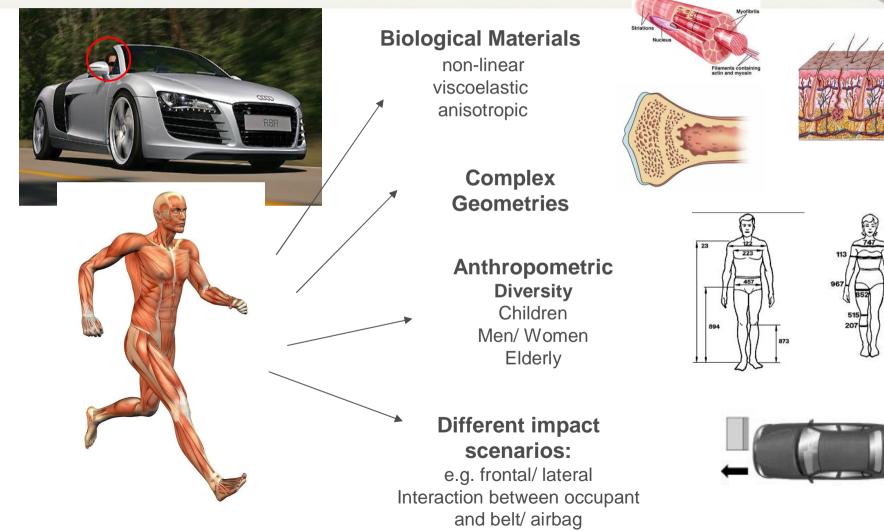


# **Human Models: Challenges**

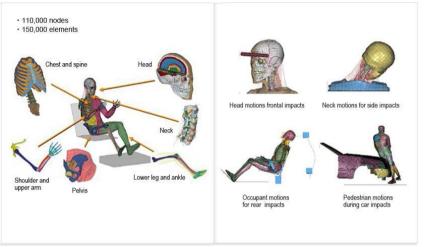


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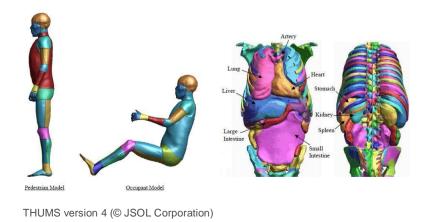
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THUMS version 3 (© JSOL Corporation)



• FE Human Model

- Developed by Toyota Motor Corporation and Toyota Central R&D Labs
- Human-like behaviour in crash
  - Human-like kinematics
  - Realistic loading representation in crash
- Representing American male body 50th percentile size (175cm, 77kg)
- Available in different versions

Injury Mode	Version 1	Version 3	Version 4	
Fracture and Tendon rupture	Yes	Yes	Yes	
Brain damage	No	Yes	Yes	
Organ damage	No	No	Yes	
© JSOL Corporation	Used w	ithin THUMS Use	Community	



# Motivation

- Common motivation and interest of project partners to constantly improve vehicle and traffic safety
  - Implementation of HBMs as tool for the evaluation of passive safety systems
- Harmonisation, provision and maintenance of THUMS in 3 different codes (DYNA, VPS, Abaqus)
  - No uniform model available among project partners
    - THUMS was further developed by several project partners
      - Daimler: shoulder, improved mesh



© Daimler AG

Autoliv: thorax





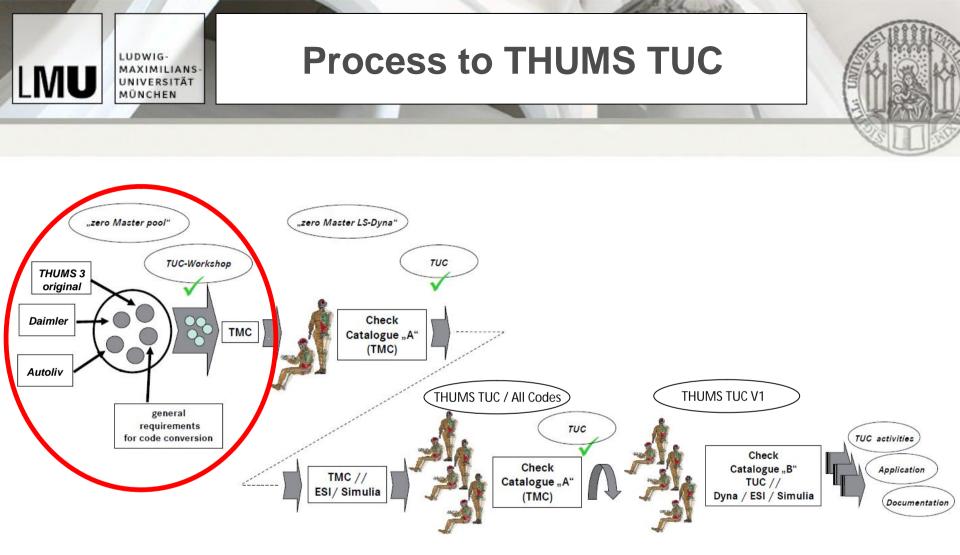
© Daimler AG



# **Aims and Objectives**

#### Harmonisation, provision and maintenance of a FE – Human Body Model for vehicle and traffic safety application

- Safeguarding effective and robust usability of THUMS by implementation of a dedicated tool management, support and documentation.
- ✓ Initiation of further research activities to improve biomechanical model quality and validity.
- Exchange and documentation of research results and initiation of further research activities
- Set up a platform to share and exchange pre-competitive know-how and experience with the application of THUMS.
- Discuss and formulate framework requirements to establish a permanent institution by the end of this project to continue this platform approach.
- ✓ Gain new members contributing to the project



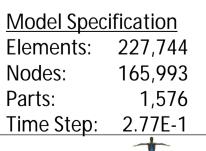


# **Model Integration (TMC)**

 TUC 1st Master Model was developed integrating Daimler Pedestrian and Occupant Models and Autoliv Occupant Model.



Daimler Pedestrian
Daimler Occupant
Autoliv Occupant



Body Region	Daimler Pedestrian	Daimler Occupant	Autoliv Occupant
Head			
Neck			x
Thorax		x	x
Abdomen			x
Pelvis		x	x
Extremities	x		

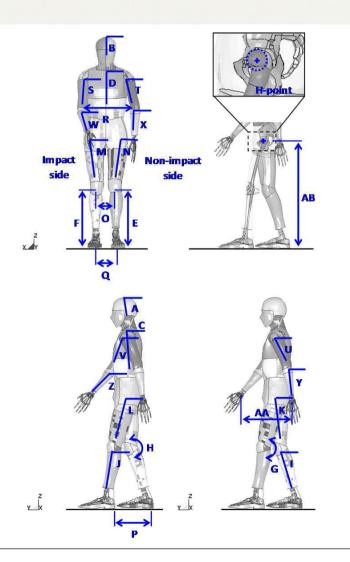


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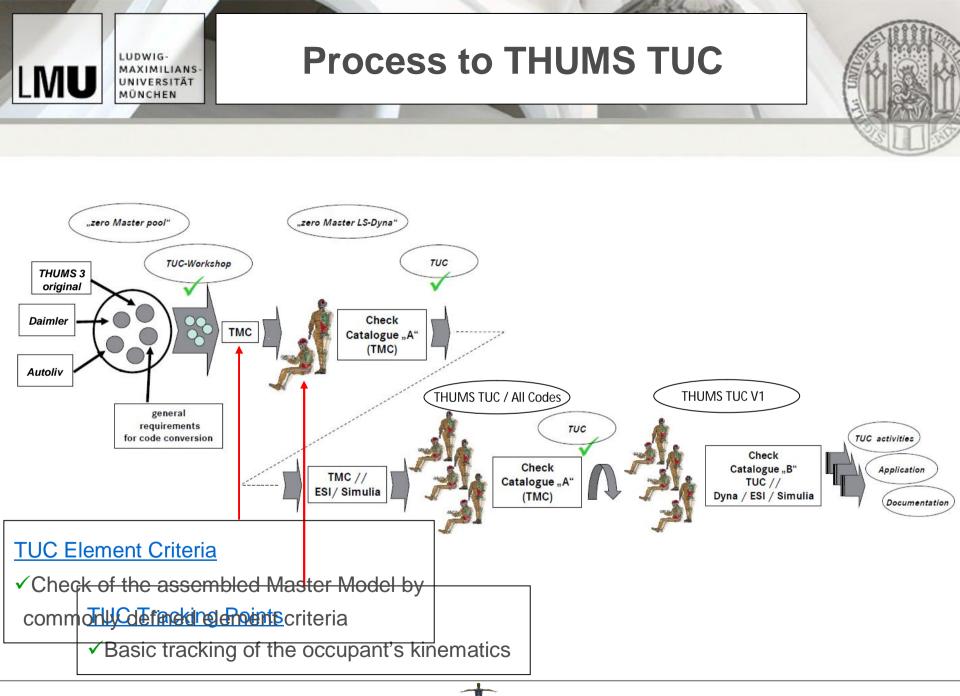
# **Positioning for Pedestrian (TMC)**

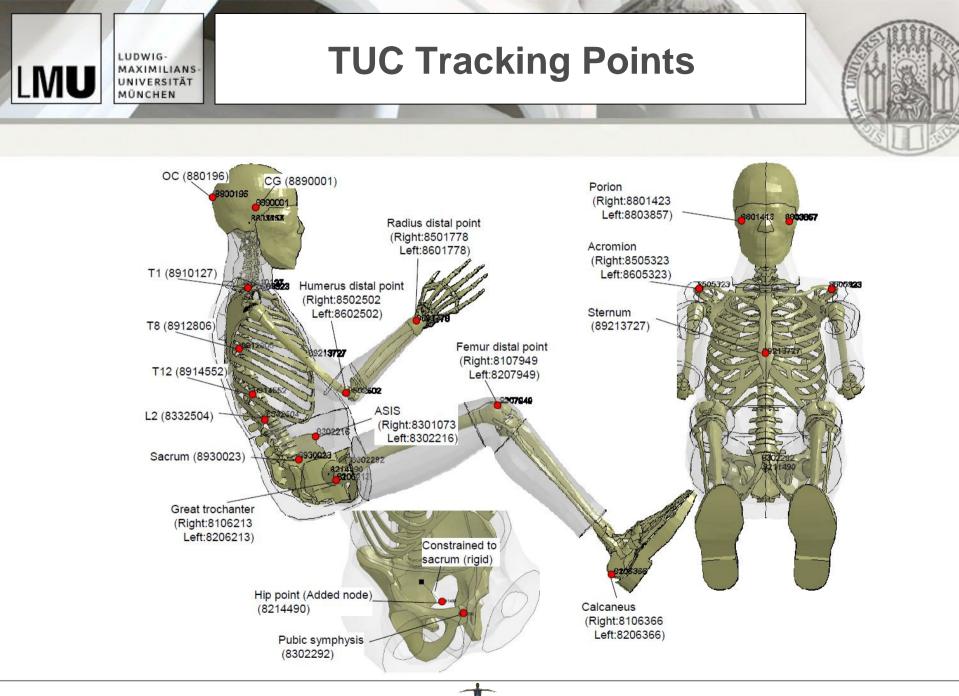


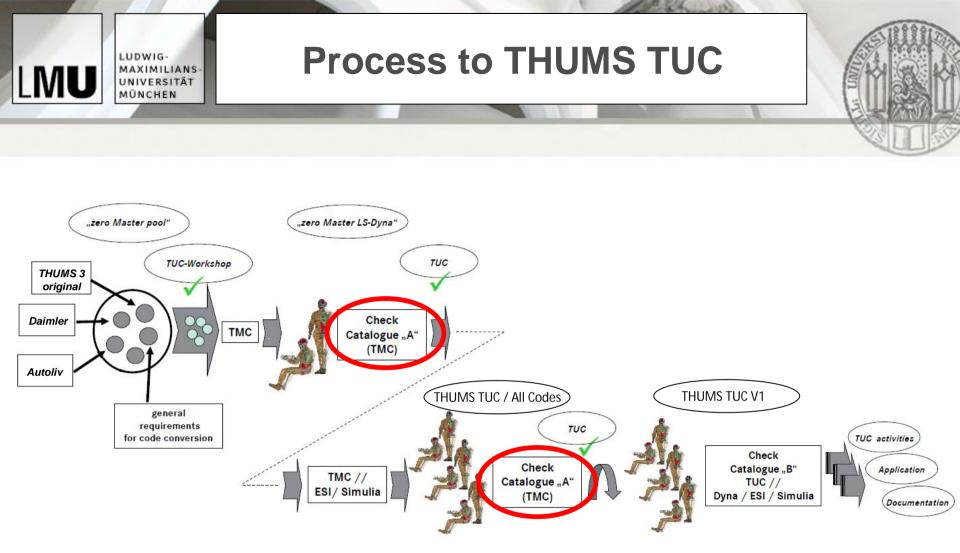


- ✓ THUMS TUC pedestrian obtained by positioning the occupant model
- ✓ Positioned to SAE J2782 (EuroNCAP T/P V7 compatible)

Segment	Aspect	Units	Axis	SAE J2782	TUC AM50
Head angle		deg	About X	83 ±5	83
		deg	About Y	90 ±5	90
Torso angle		deg	About X	83 ±5	85
		deg	About Y	90 ±5	90
Knee height	Non-impact side	mm	Z	505 ±10	505
	Impact side	mm	Z	520 ±10	493
Knee bend angle	Non-impact side	deg	Angle in YZ plane	171 ±5	182
	Impact side	deg	Angle in YZ plane	164 ±5	182
Tibia angle	Impact side	deg	About X	73 ±5	79
i ibia aligie	Non-impact side	deg	About X	98 ±5	100
	Impact side	deg	About X	89 ±5	78
Femur angle	Non-impact side	deg	About X	107 ±5	97
remui angle	Impact side	deg	About Y	87 ±5	84
	Non-impact side	deg	About Y	94 ±5	96
Knee to knee width		mm	Х	280 ±10	171
Heel to heel distance		mm	Y	310 ±10	311
		mm	Х	280 ±10	97
Elbow to elbow width		mm	Х	420 ±10	436
	Impact side	deg	About Y	-	95
Upper arm angle	Non-impact side	deg	About Y	-	78
upper arm angle	Non-impact side	deg	About X	-	65
	Impact side	deg	About X	-	111
	Impact side	deg	About Y	-	82
Lower arm angle	Non-impact side	deg	About Y	-	269
Lower arm angle	Non-impact side	deg	About X	-	-89
	Impact side	deg	About X	-	136
wrist to wrist distance		mm	Y	-	410
H-point		mm	Z	-	949



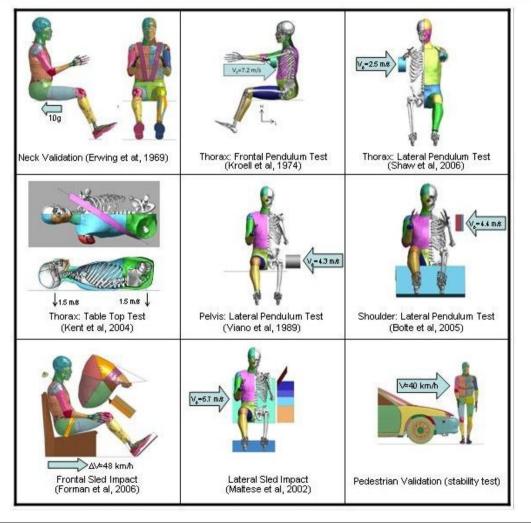






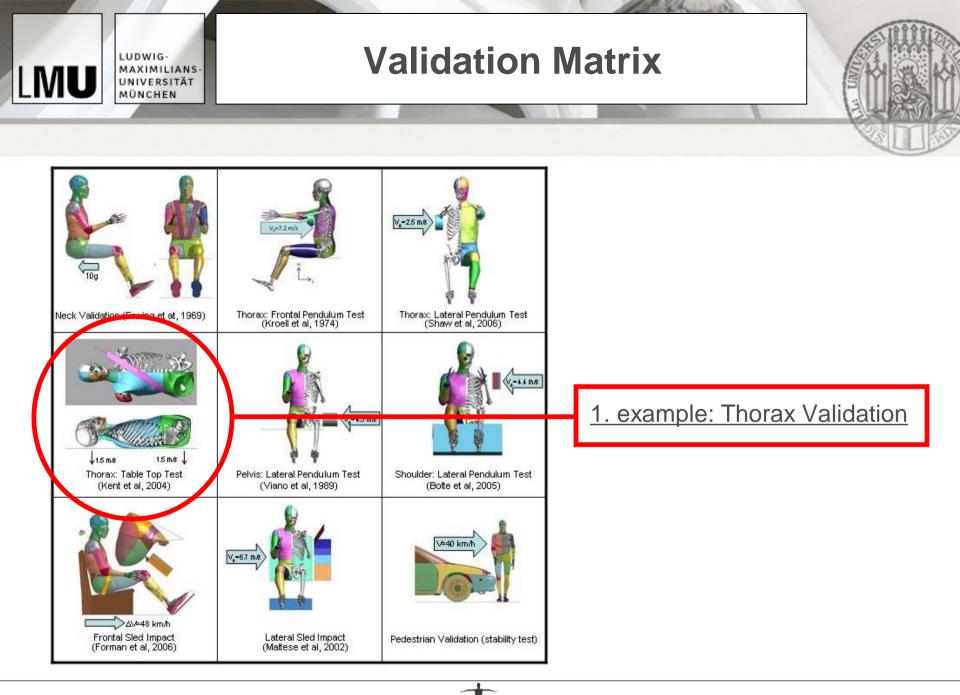
# **5**-1

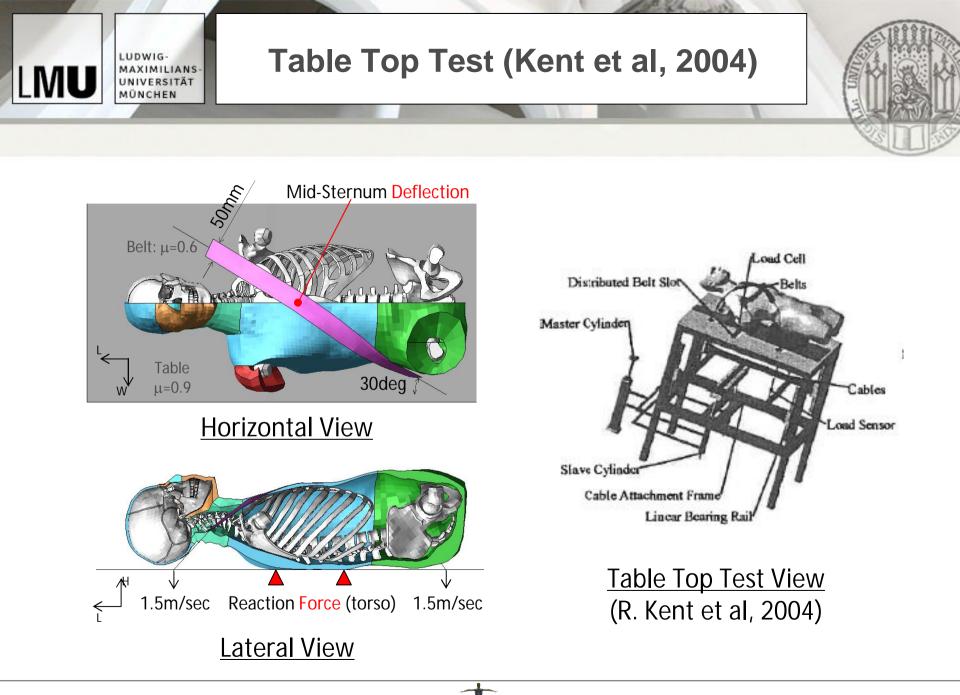
# **Validation Matrix**

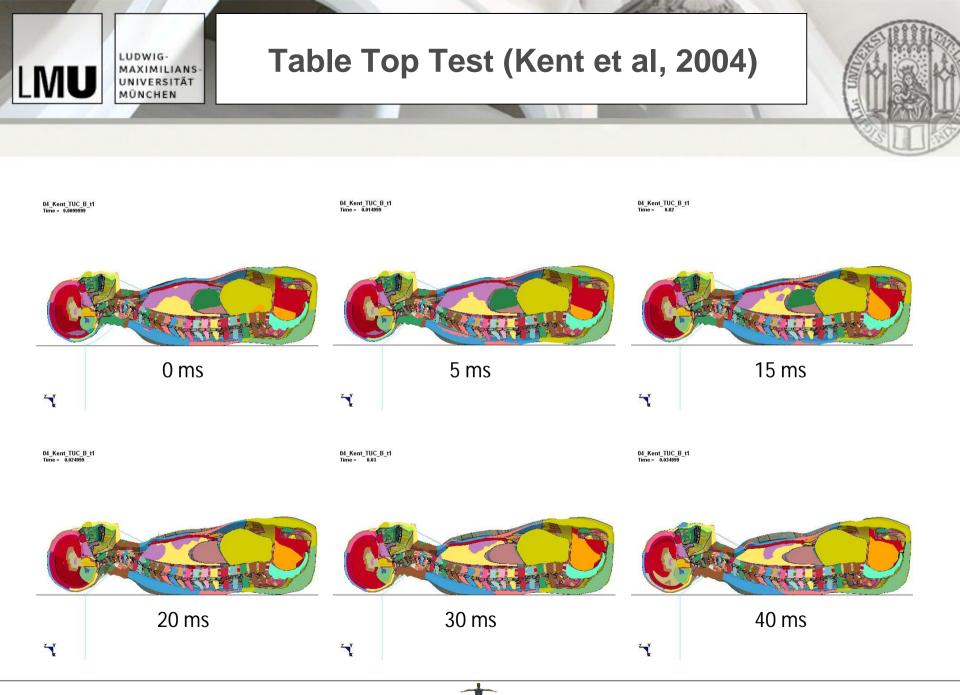


#### Validation Catalogue A

- ✓ 9 validation cases on neck, thorax, pelvis, shoulder, whole body (occupant and pedestrian)
- ✓ Basic validation checks
- ✓ Robustness checks
- ✓ Basic tracking
- Cases defined for occupant and pedestrian validation independently



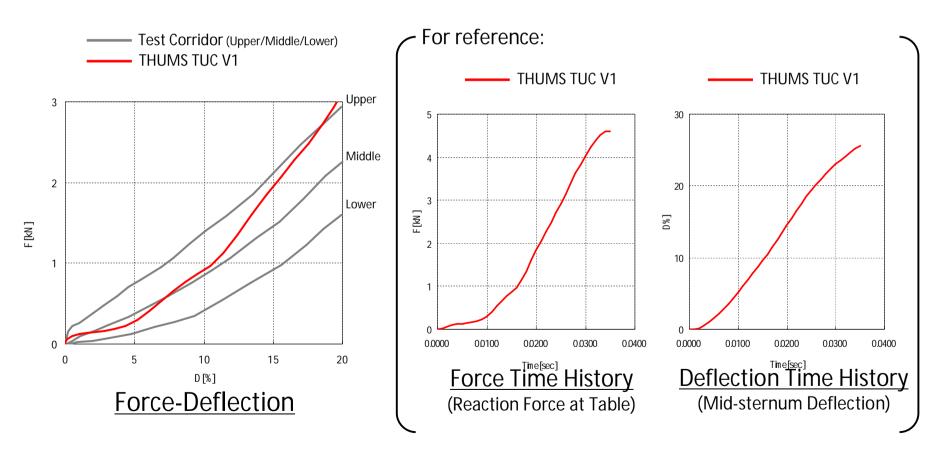






### Table Top Test (Kent et al, 2004)

### ✓ Calculated force-deflection curve in agreement with test corridor.

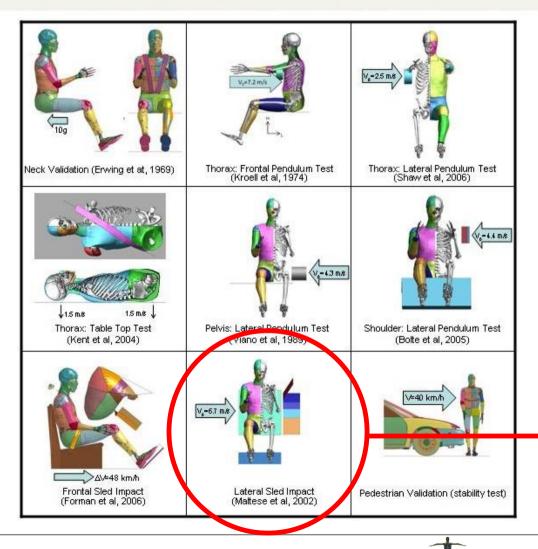




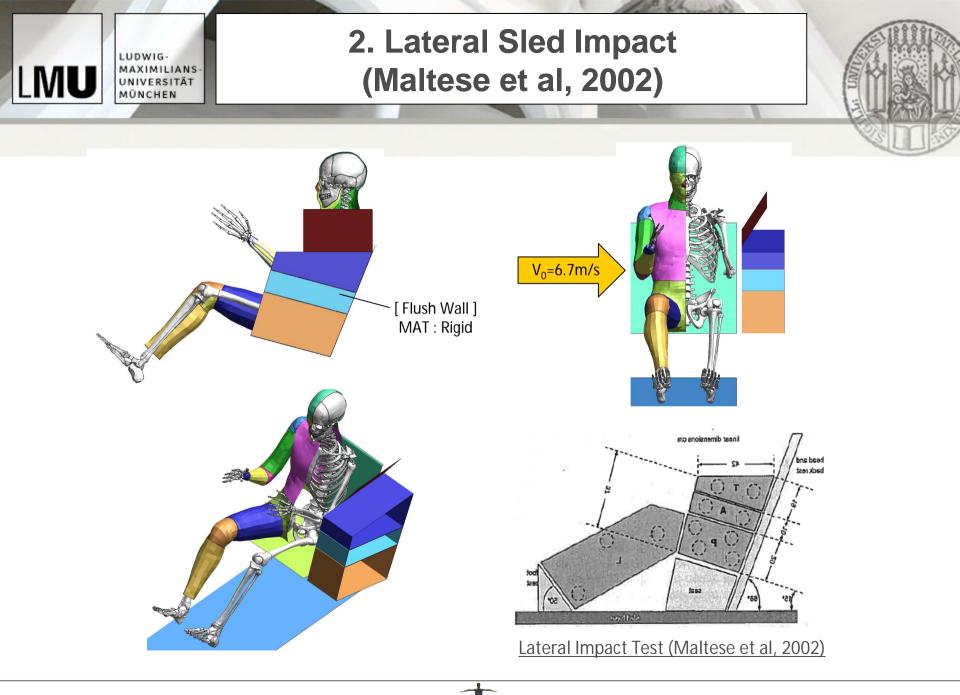
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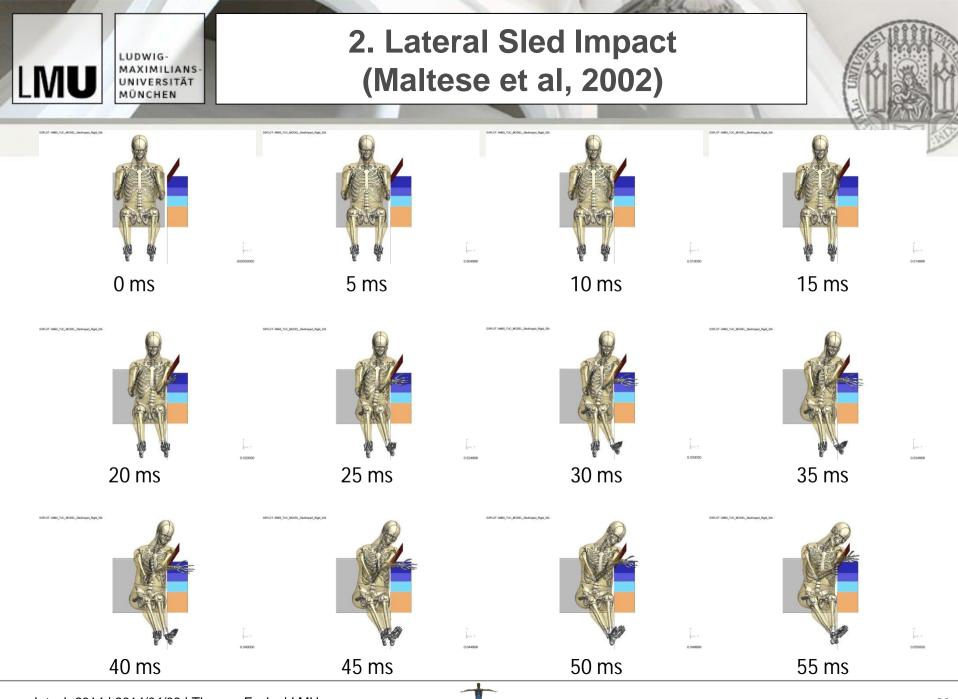
# **Validation Matrix**

es a



#### 2. example: Lateral Sled Impact



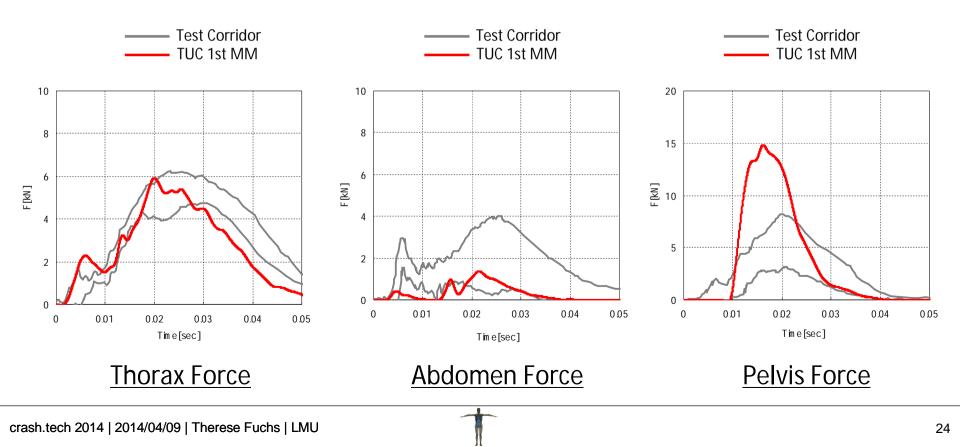


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2. Lateral Sled Impact (Maltese et al, 2002)

✓ Thorax force: Good match.
✓ Abdomen force: Lower boundary of test corridor.
✓ Pelvis force: Greater peak.





### 2. Lateral Sled Impact (Maltese et al, 2002)

Differences in pelvis force possibly caused by difference in the initial posture and surface geometry between test subject and simulation model



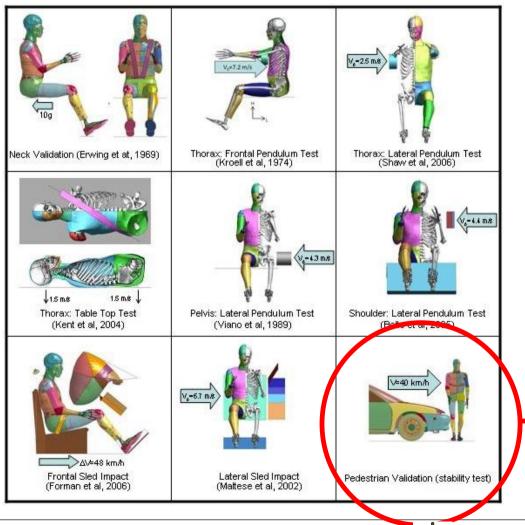
Lessley et al. (2010)



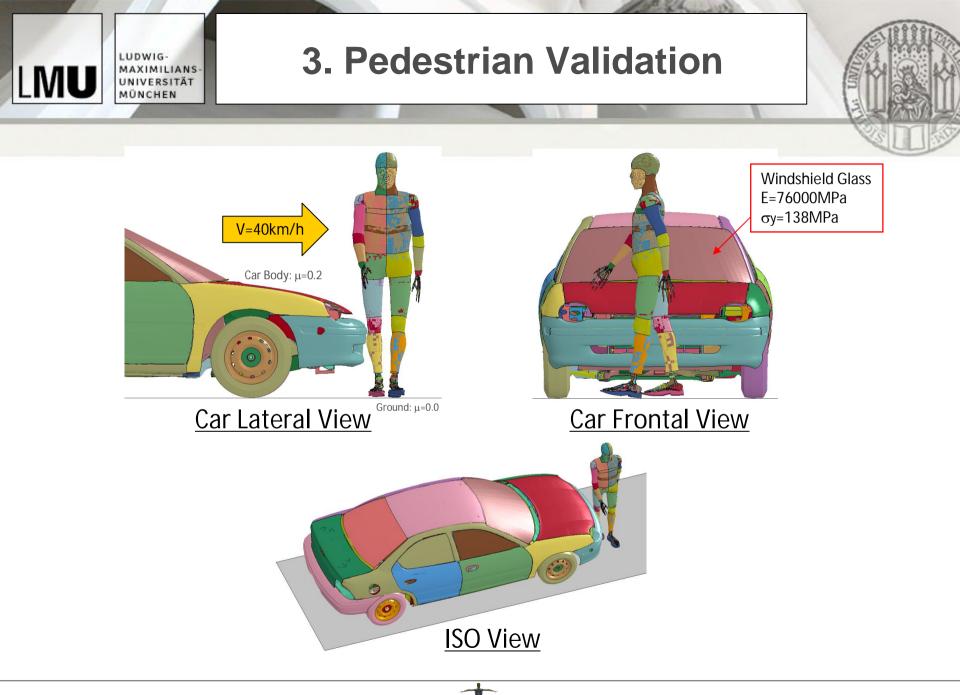
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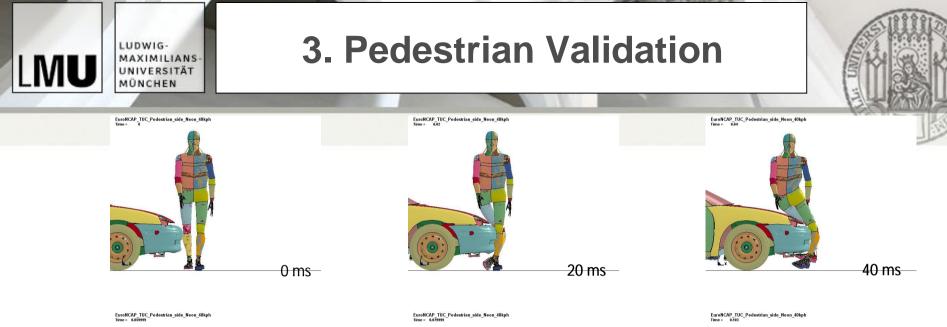
# **Validation Matrix**

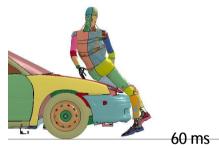
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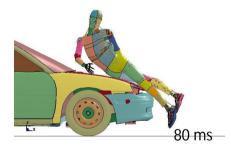


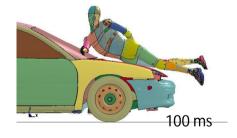
3. example: Pedestrian Validation



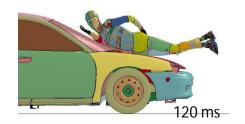


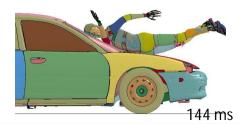


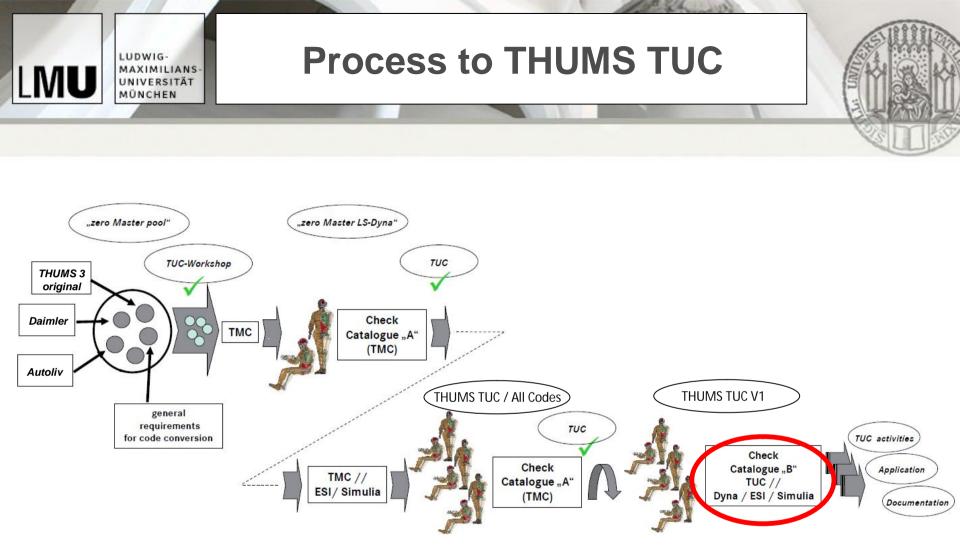


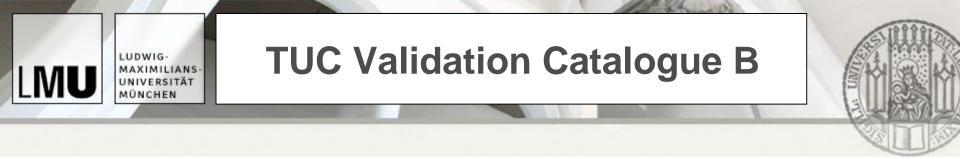


EuroNCAP\_TUC\_Pedestrian\_side\_Neon\_40kph Time = 0.123 EuroNCAP\_TUC\_Pedestrian\_side\_Neon\_40kph Time = 0.143









- ✓ List of validation cases (approx. 35) for biomechanical assessment
- ✓ Currently reviewed: over 50 references checked for their suitability



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# **THANK YOU!**

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